

FIG. 1A

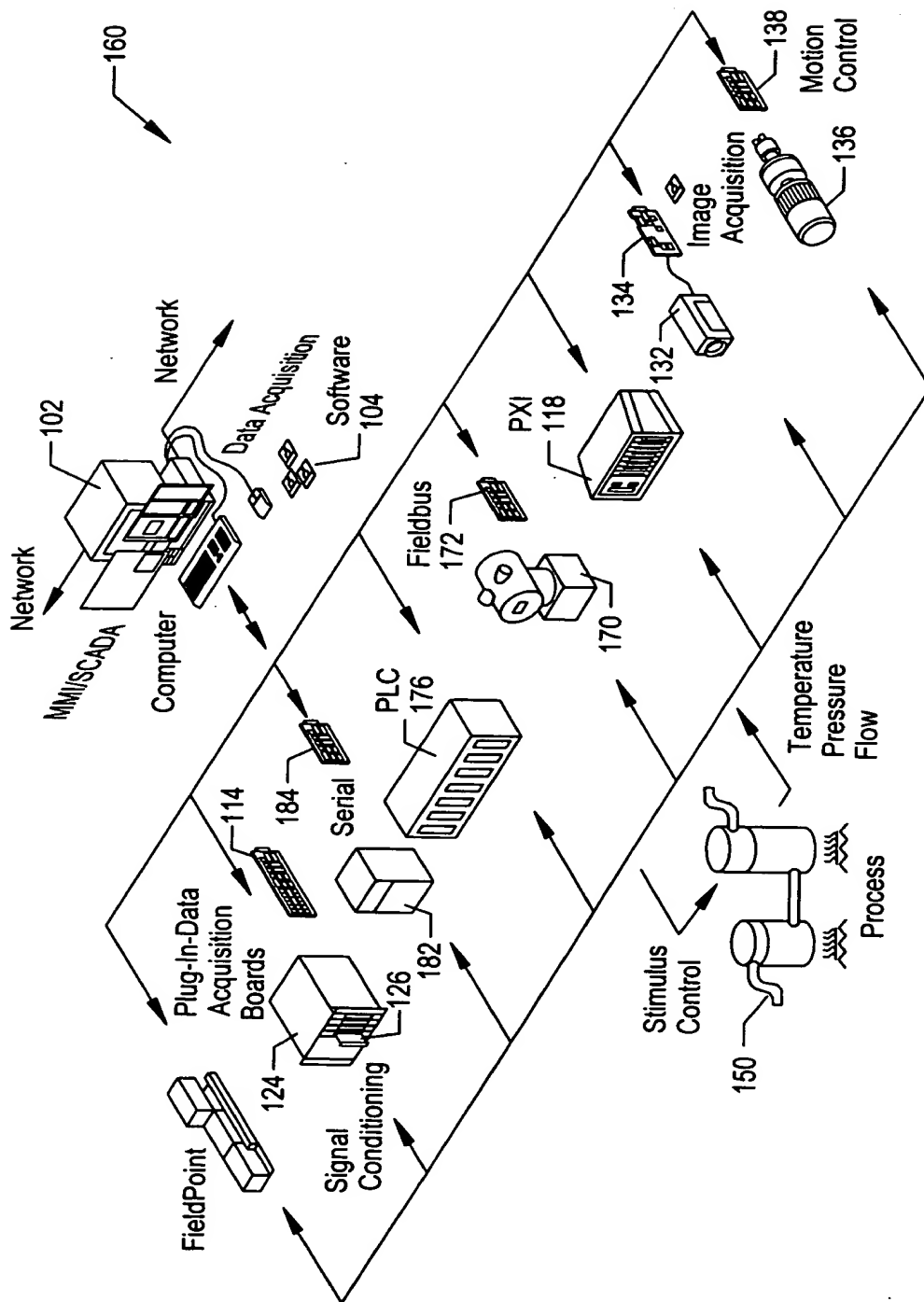


FIG. 1B

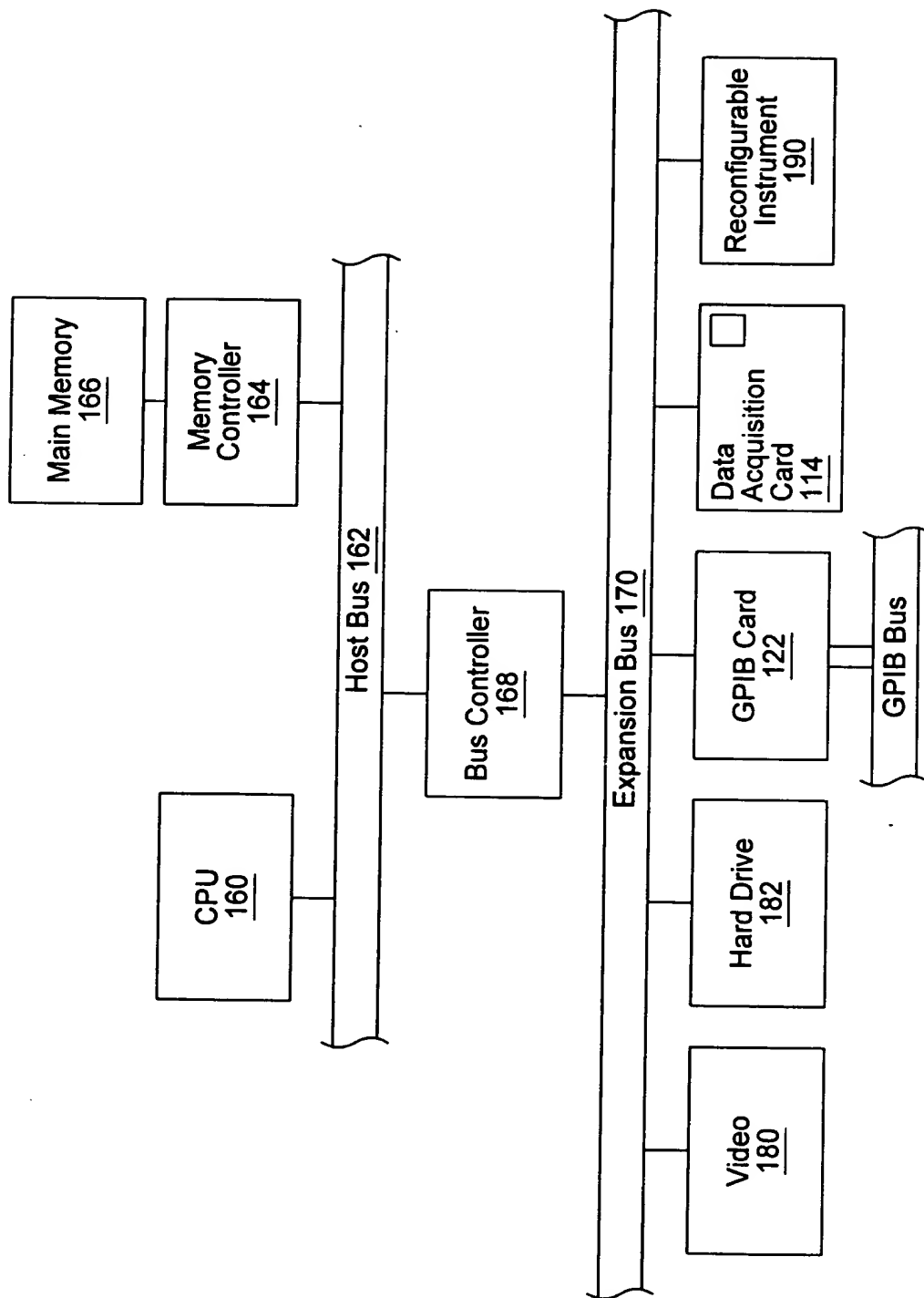


FIG. 2

09940189-082701

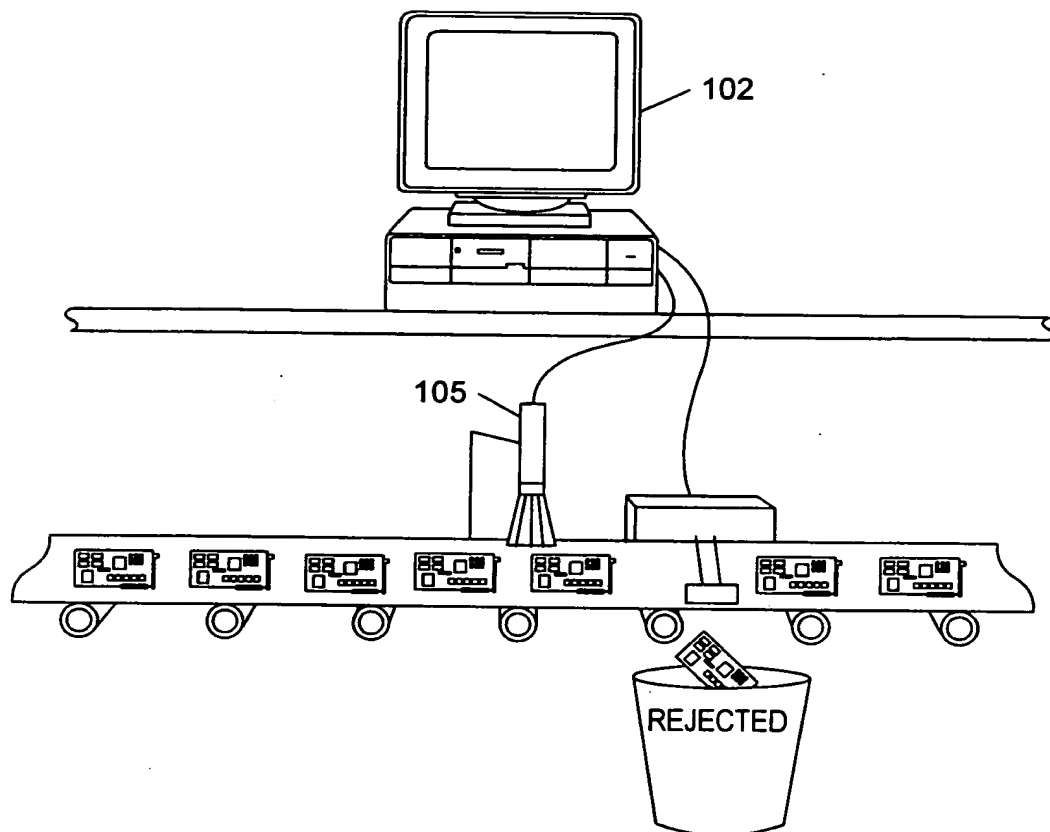


FIG. 3

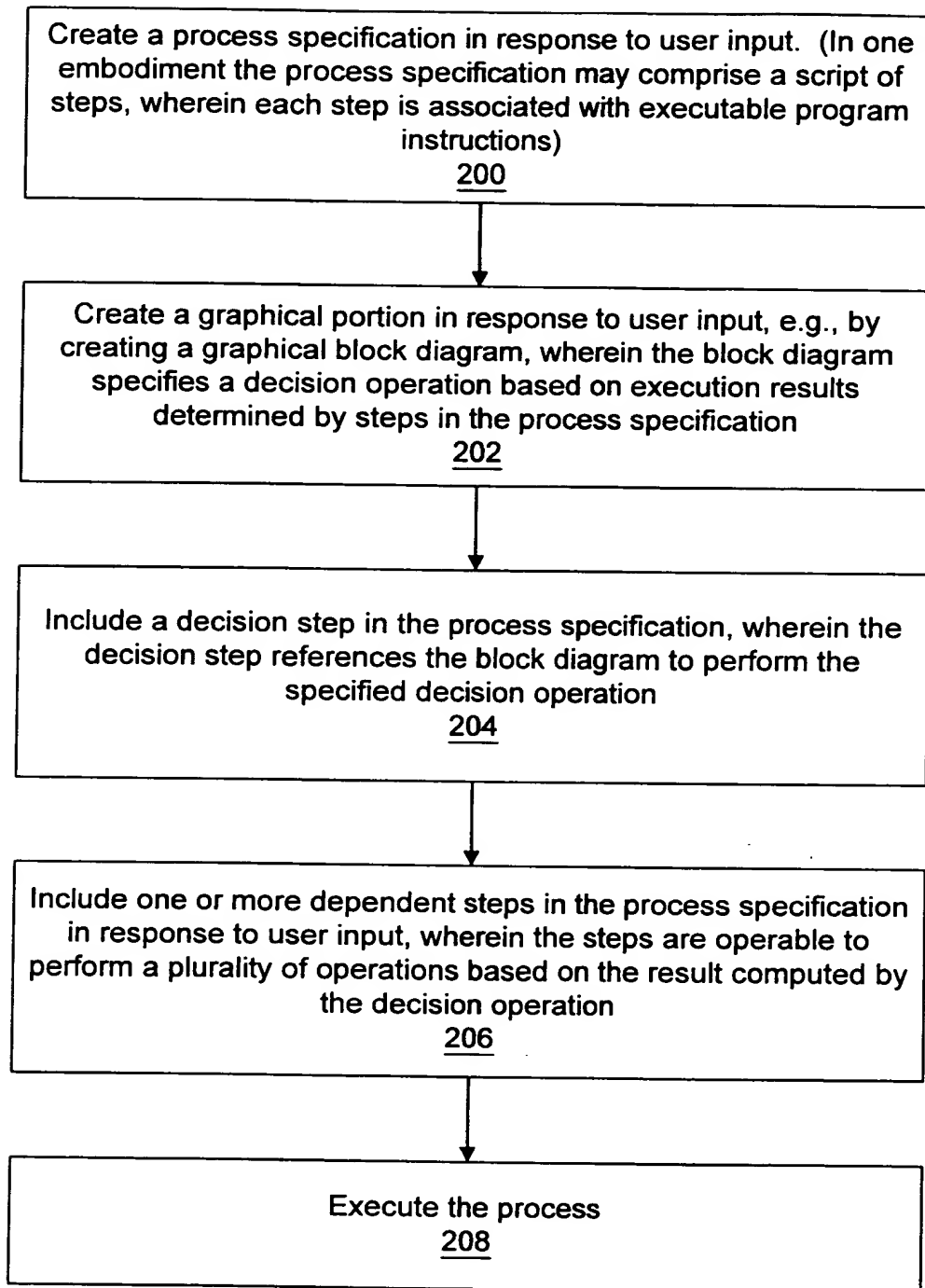


FIG. 4

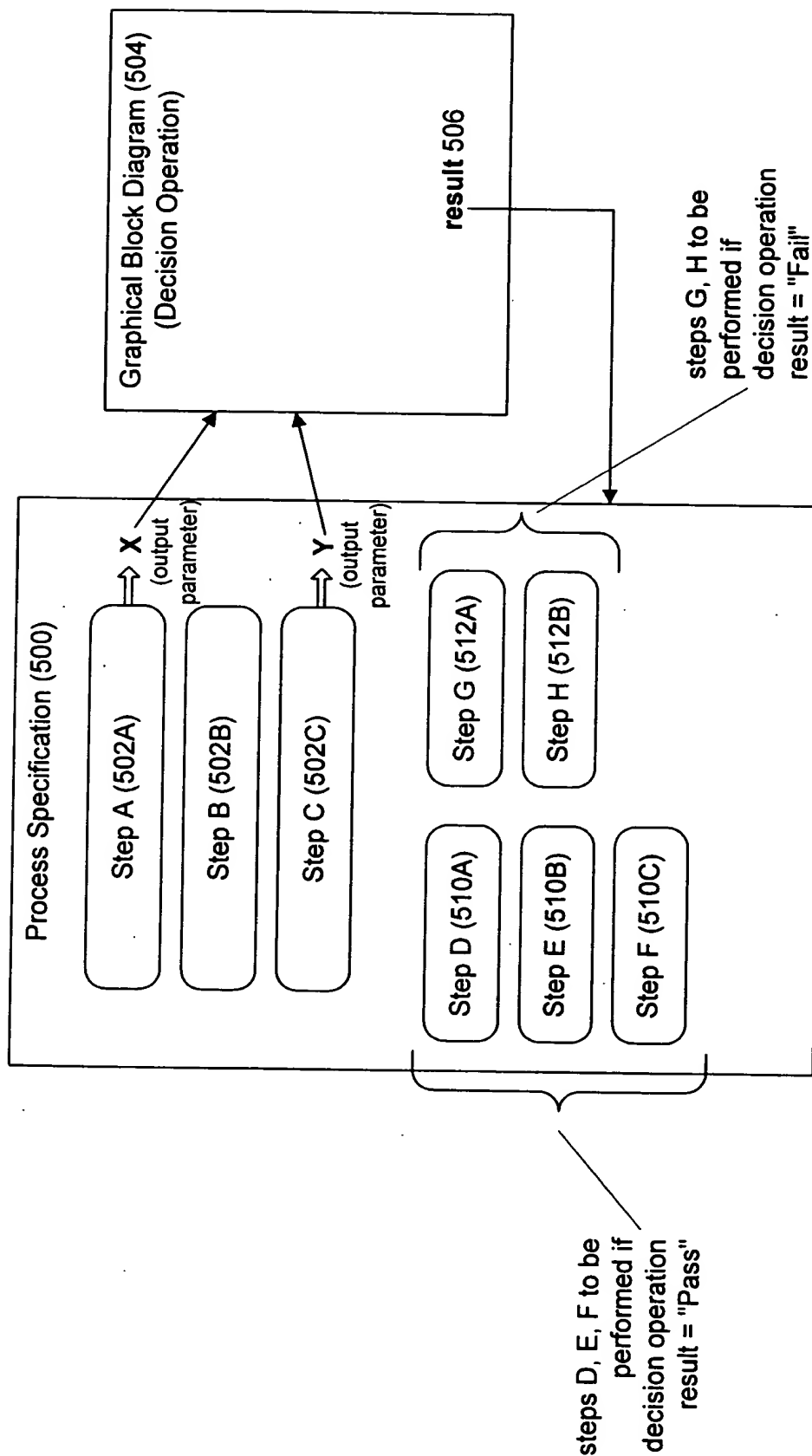


FIG. 5

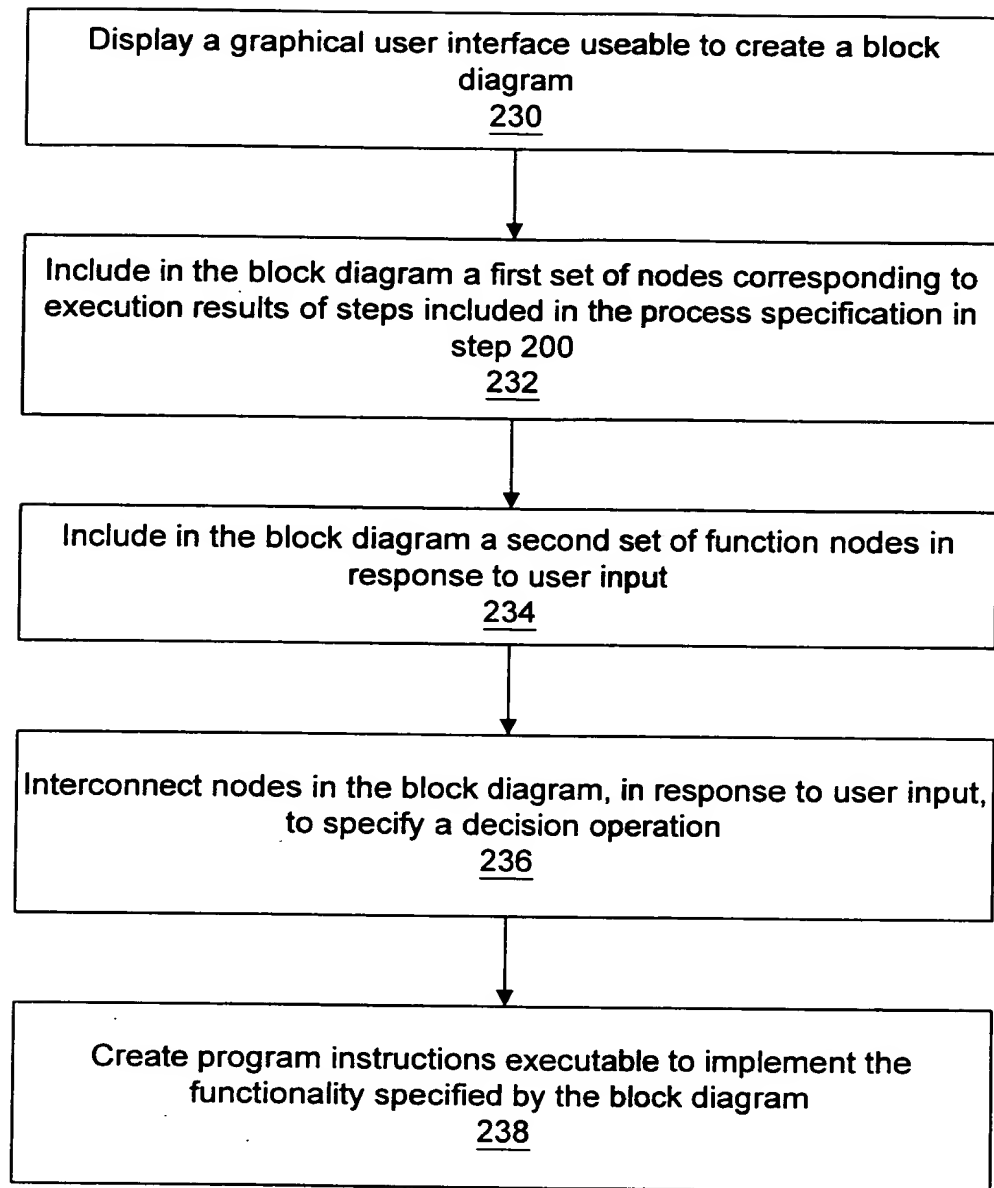


FIG. 6

09940189-082701

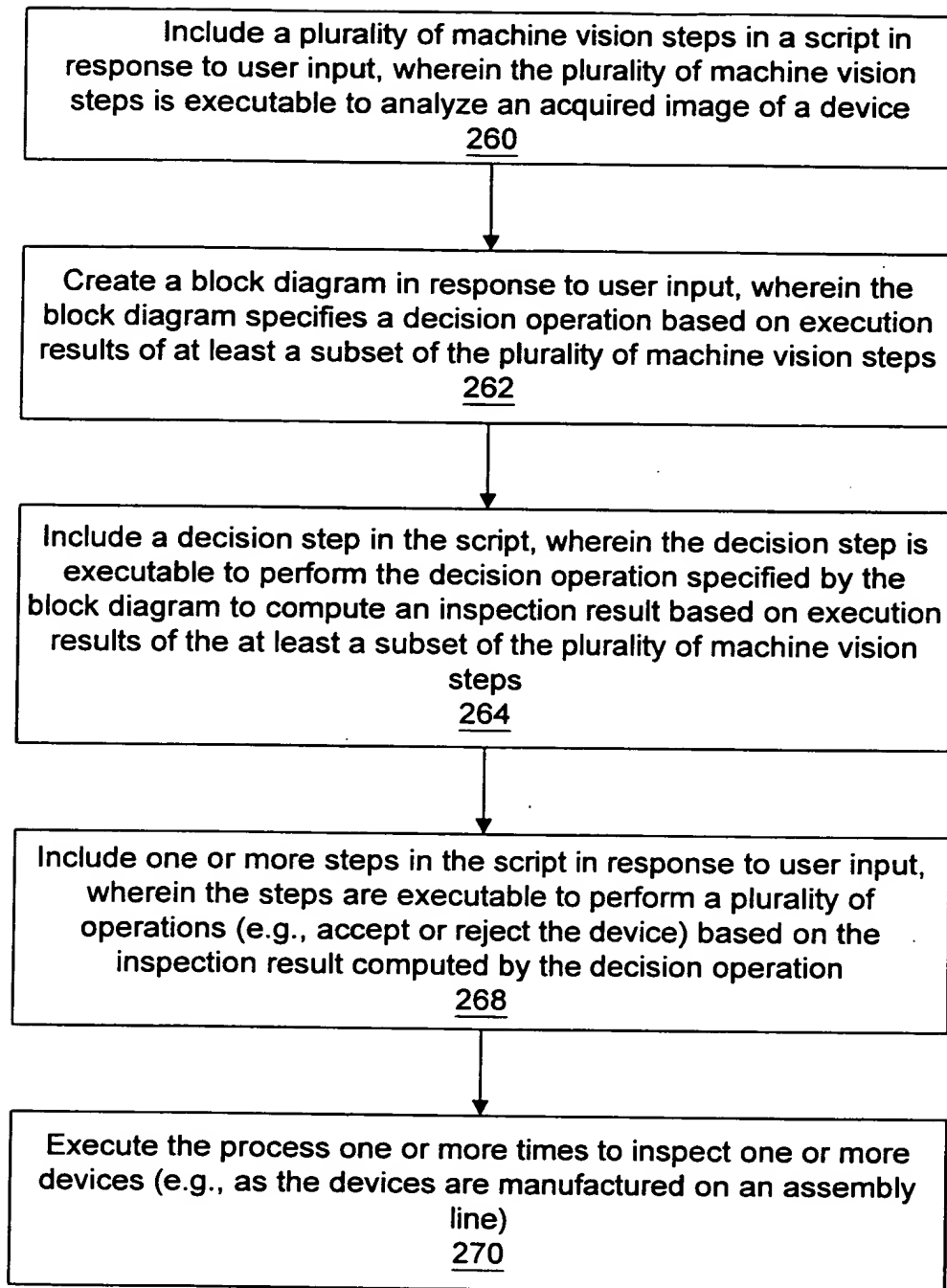


FIG. 7

102280" 68104560

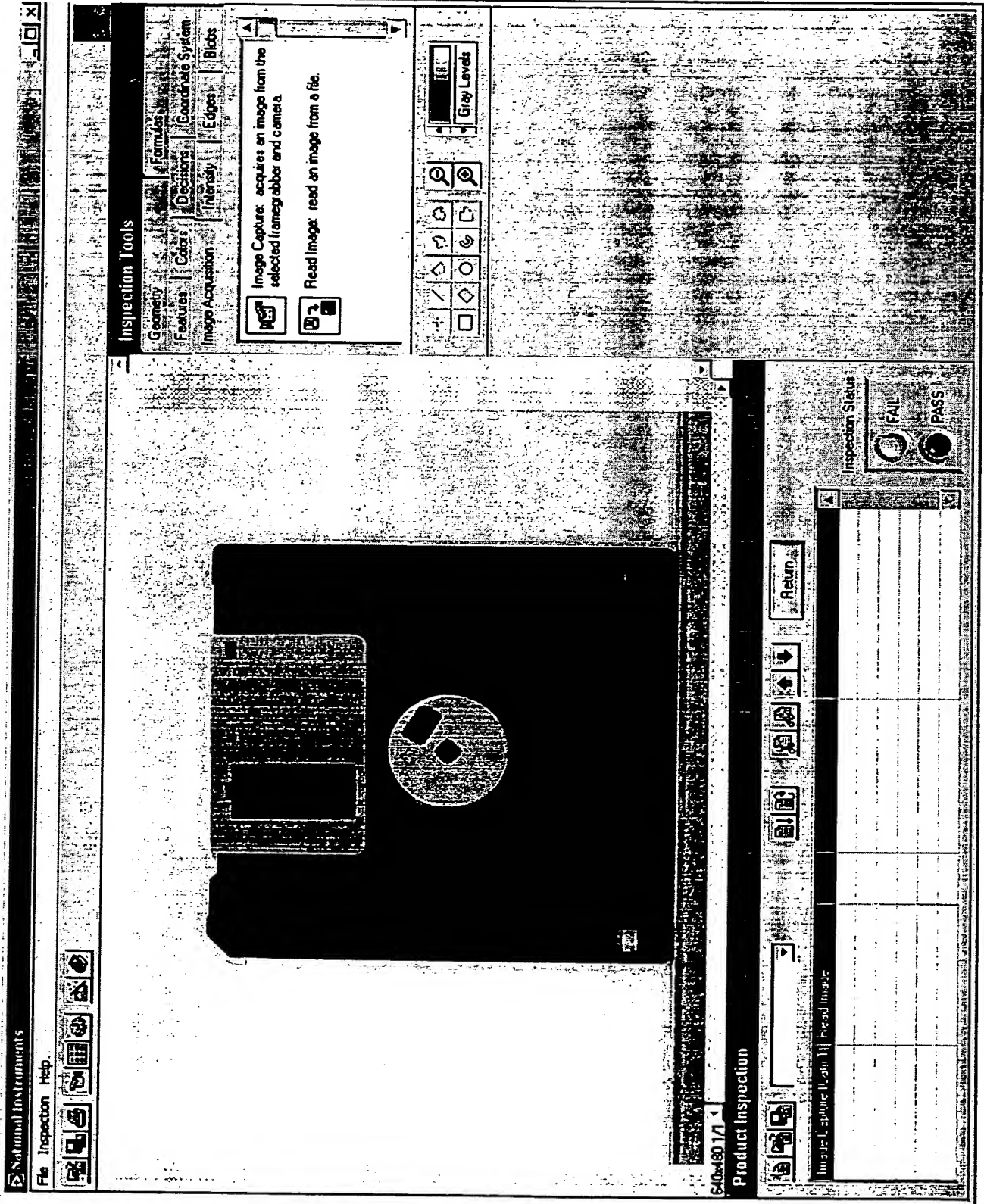


FIG. 8

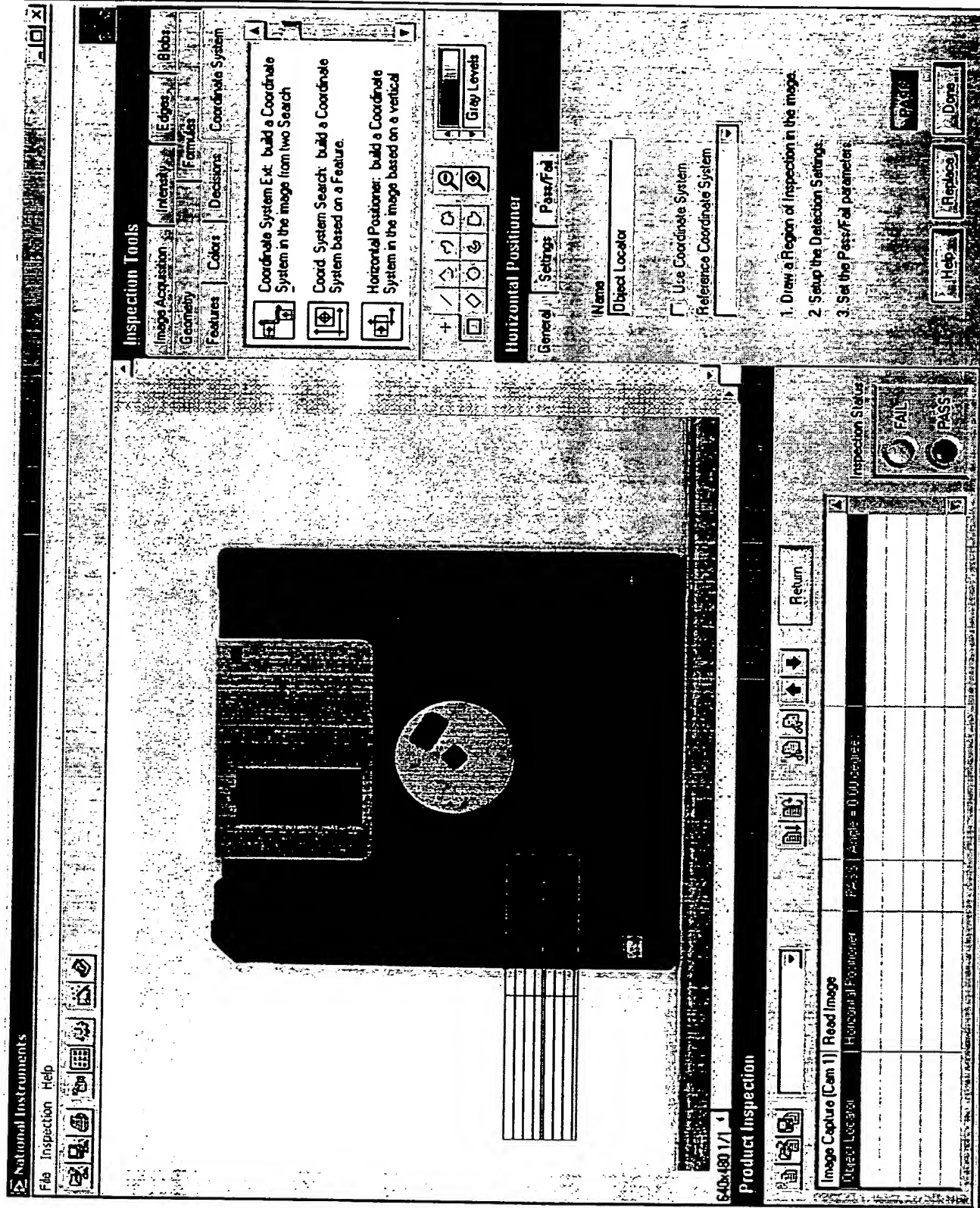


FIG. 9

10/280" 68T04660

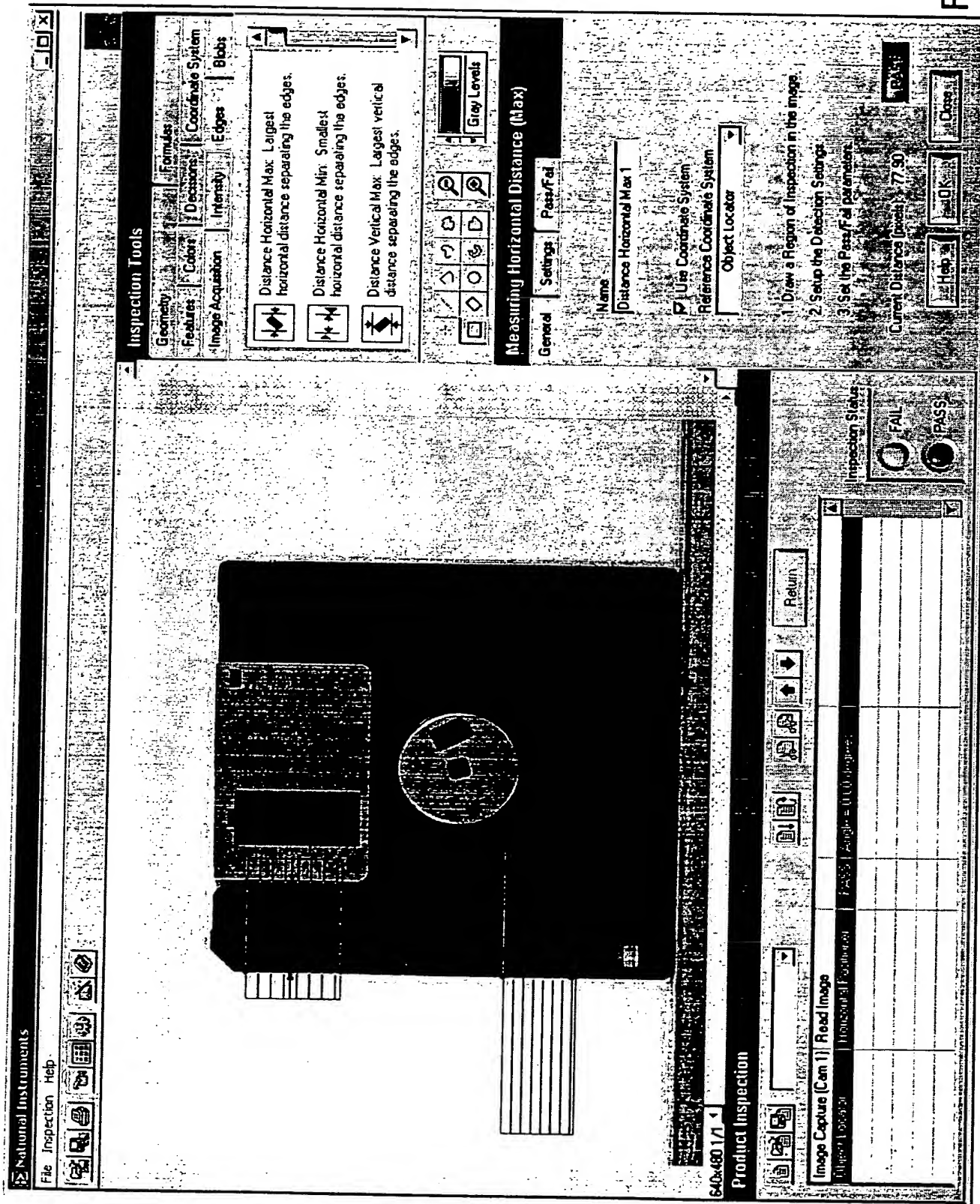


FIG. 10

Measuring Horizontal Distance (Max)

General Settings Pass/Fail

Name:

☒ Use Coordinate System
Reference Coordinate System

1. Draw a Region of Inspection in the image.
2. Setup the Detection Settings.
3. Set the Pass/Fail parameters.

Current Distance (pixels): 7790

FIG. 11

107280" 58T04560

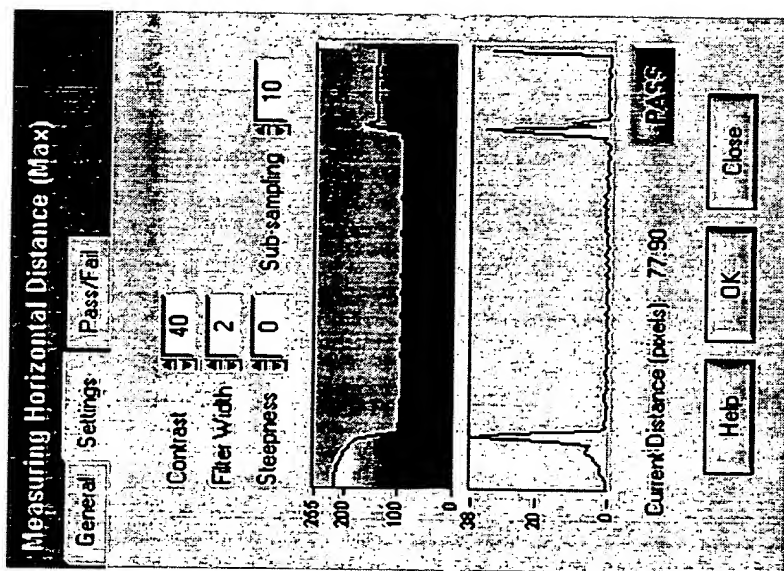


FIG. 12

FDL280" 58T04660

Measuring Horizontal Distance (Max)

General Settings Pass/Fail

Pass Conditions

☒ Minimum Distance (Pixels) 75.00

☒ Maximum Distance (Pixels) 80.00

Current Distance (pixels): 79.90

UPASS

Help Replace Done

FIG. 13

102280-63104560

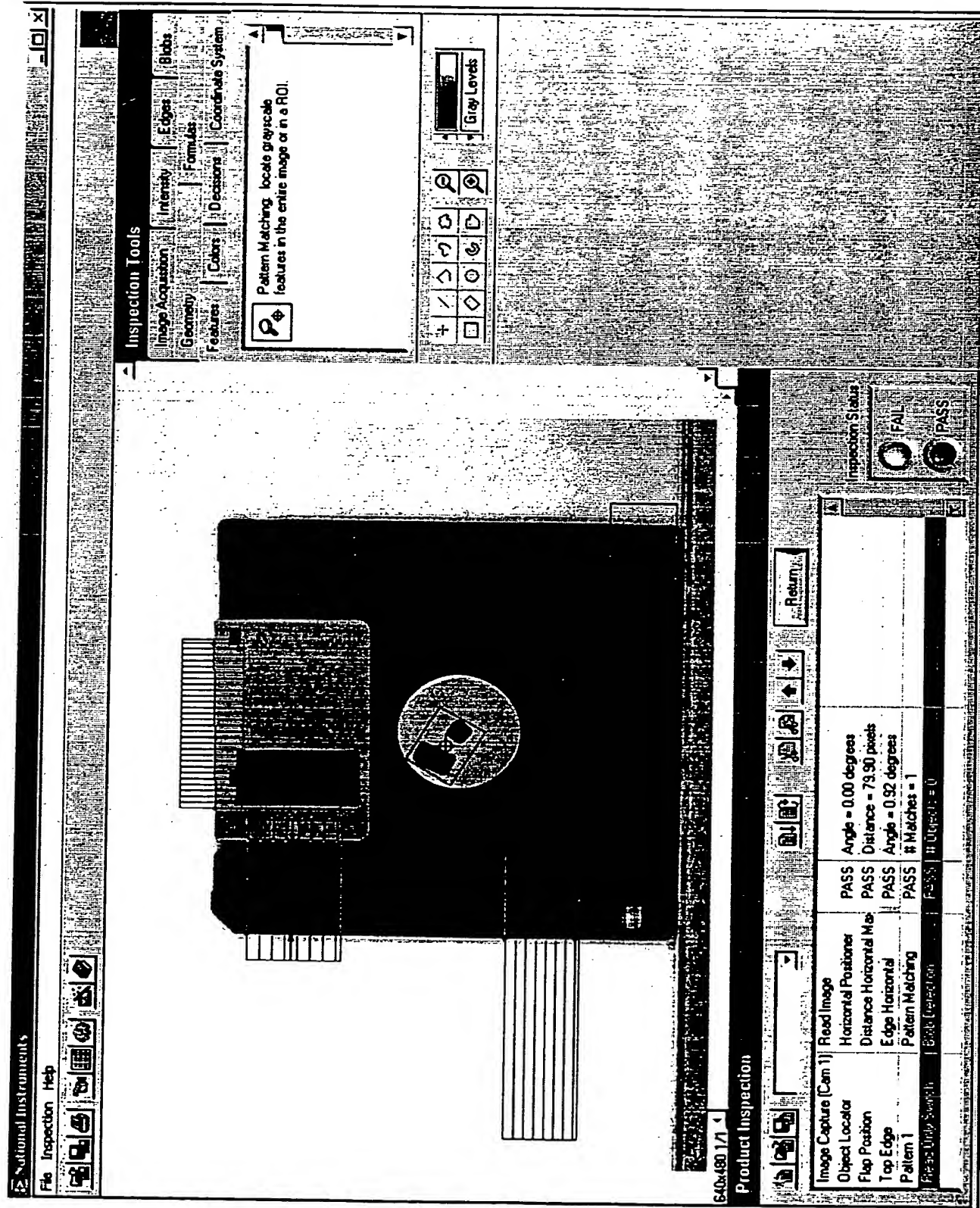


FIG. 14

Inspection Results

[illegible]

W/AM

Product Inspection

Image Capture (Cam 1)		Read Image	
Object Locator	Horizontal Positioner	PASS	Angle = 0.00 degrees
Flap Position	Distance Horizontal Max	PASS	Distance = 79.90 points
Top Edge	Edge Horizontal	PASS	Angle = 0.92 degrees
Pattern 1	Pattern Matching	PASS	# Matches = 1
Read Data Switch	Auto Detection	PASS	# Defects = 0

Inspection Status:

FAIL

PASS

FIG. 15

104230" 58404560

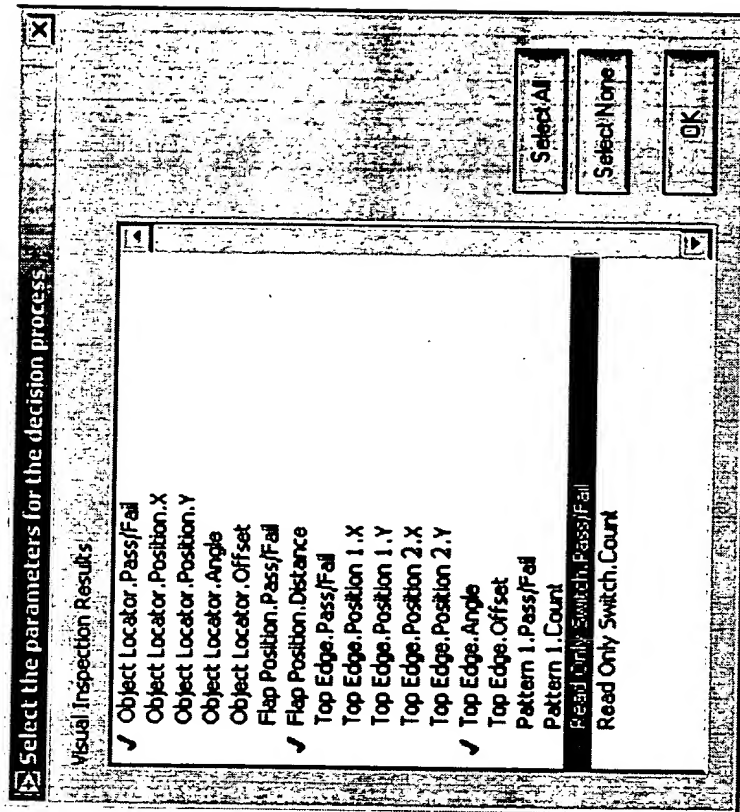
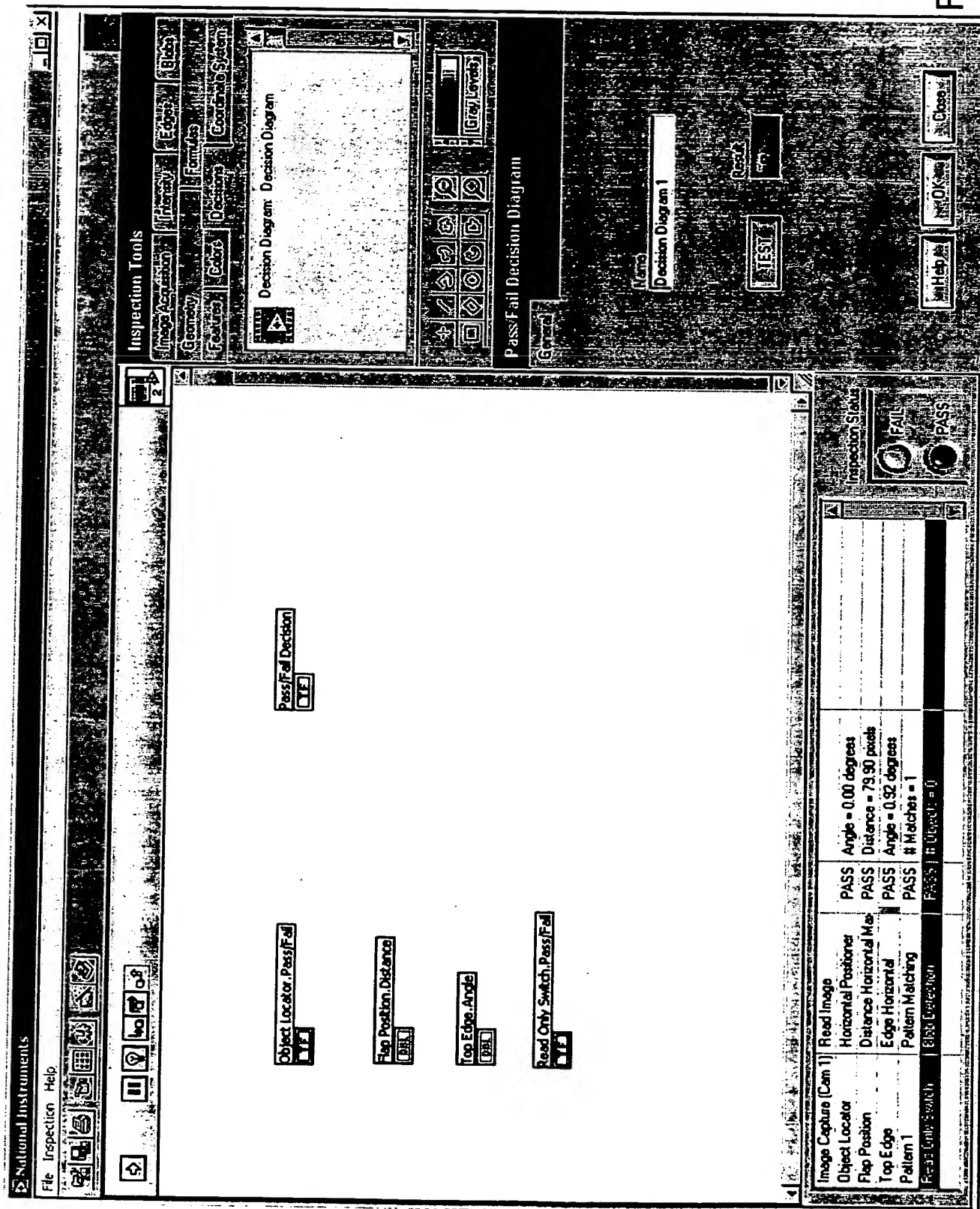


FIG. 16

09470136000000000000



102280-68104650

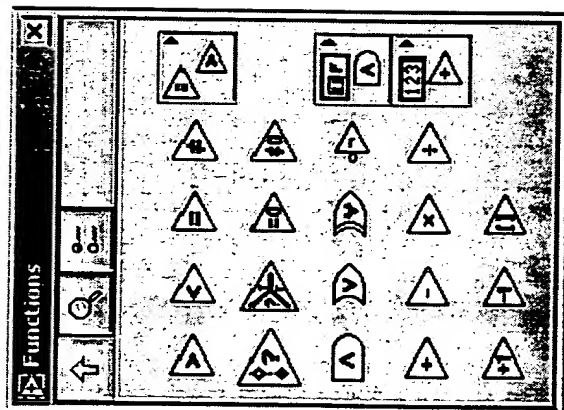


FIG. 18

104280-68104660

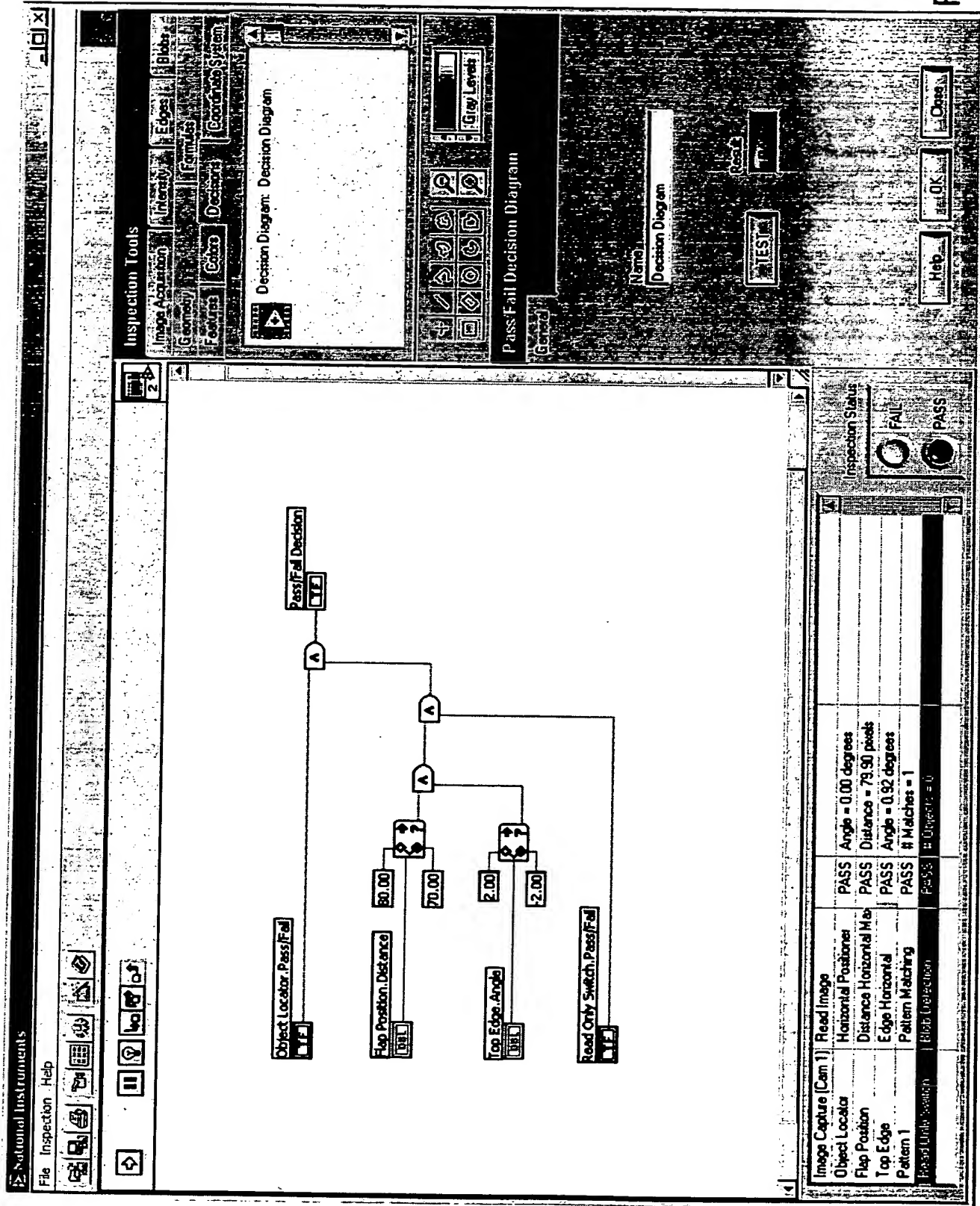


FIG. 19

104280" 68T07650

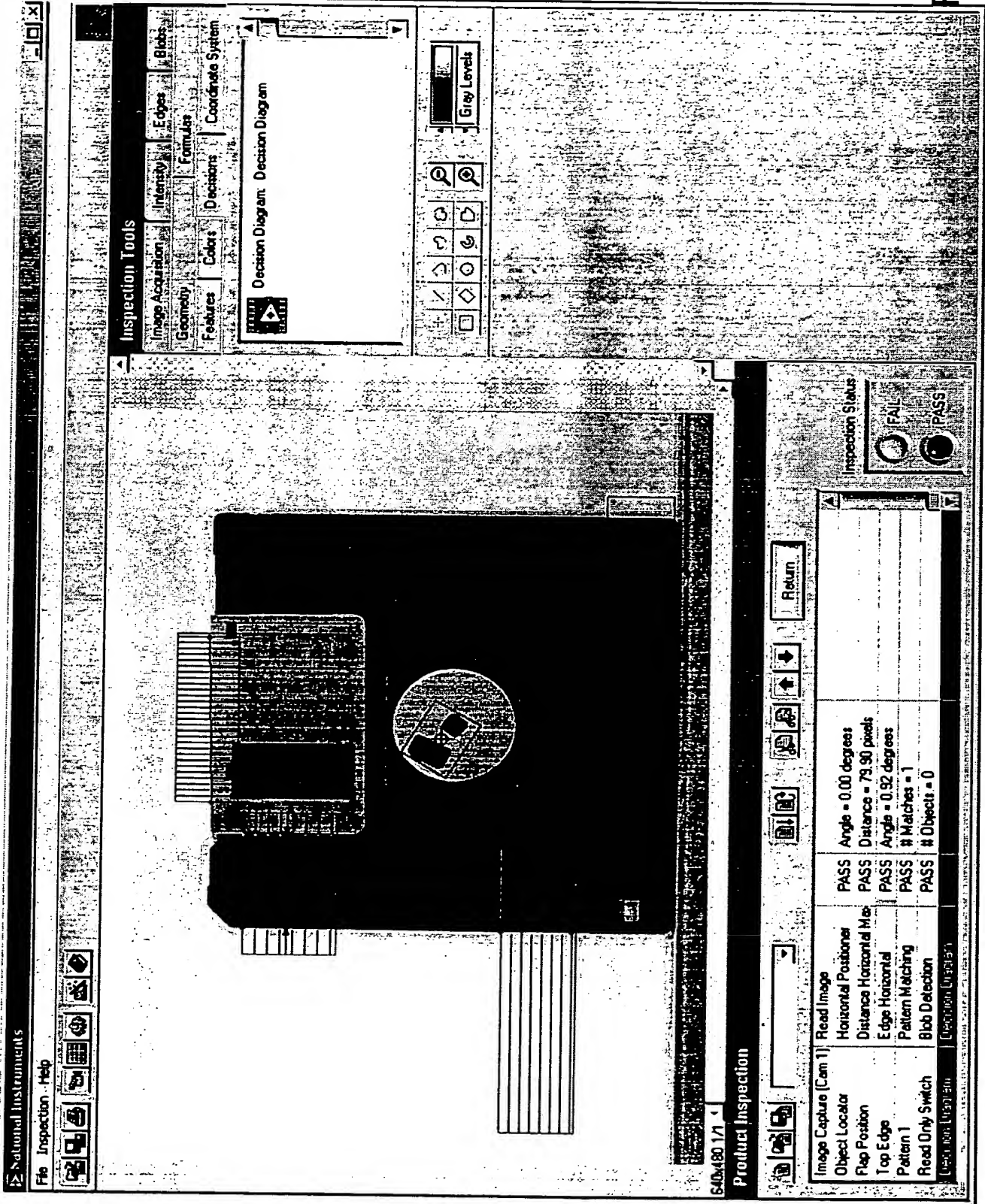


FIG. 20

10/22/00 68104660

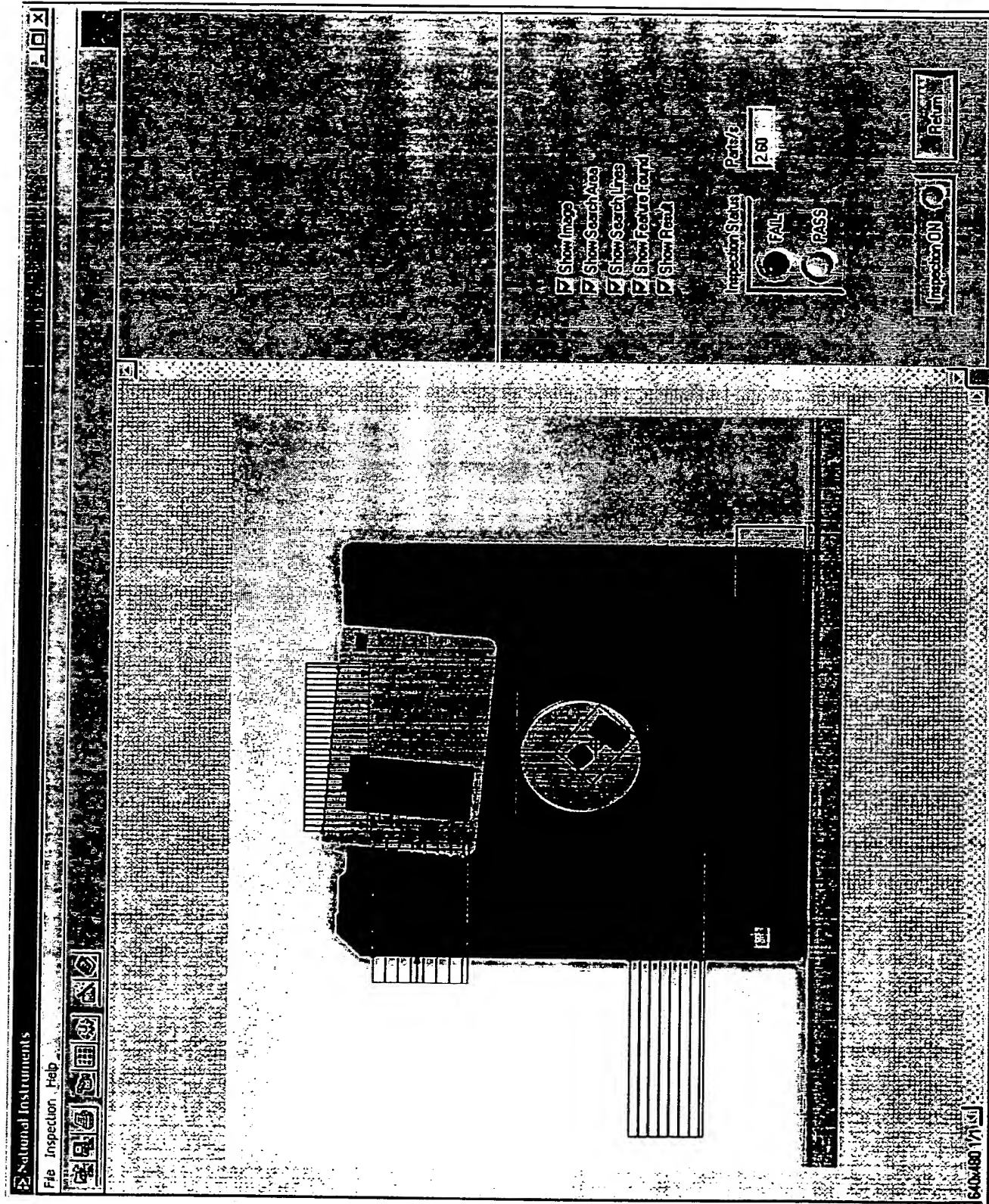


FIG. 21